Find the regular expression for the language containing all binary strings that do not contain the subsequence 111000

ECE-374-B: Lecture 3 - NFAs

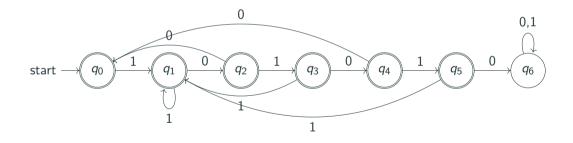
Instructer: Nickvash Kani September 05, 2024

University of Illinois at Urbana-Champaign

Find the regular expression for the language containing all binary strings that **do not** contain the subsequence 111000

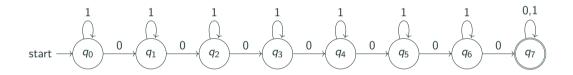
Find the regular expression for the language containing all binary strings that **do not** contain the substring 101010

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Find the regular expression for the language contains all binary strings whose $\#_0(w)\%7 = 0$ (number of 0's divisible by 7).

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Show that the following string(w) is a member of the language that:

- does not contain the subsequence 111000 or
- does not contain the substring 101010 or
- or has a number of 0's divisible by 7

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You have 30 seconds.

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- does not contain the subsequence 111000 or
- does not contain the substring 101010 or
- or has a number of 0's divisible by 7

You have 30 seconds. Pray, choose a strategy and hope you get lucky.

Does luck allow us to solve unsolvable problems?

Does luck allow us to solve unsolvable problems? New example: Consider two machines: M_1 and M_2

- *M*₁ is a classic deterministic machine.
- M₂ is a "lucky" machine that will always make the right choice.

Problem: Find shortest path from a to b

Program on M_1 (Dijkstra's algorithm):

Initialize for each node v, $\operatorname{Dist}(s, v) = d'(s, v) = \infty$ Initialize $X = \emptyset$, d'(s, s) = 0for i = 1 to |V| do Let v be node realizing $d'(s, v) = \min_{u \in V-X} d'(s, u)$ $\operatorname{Dist}(s, v) = d'(s, v)$ $X = X \cup \{v\}$ Update d'(s, u) for each u in V - X as follows: $d'(s, u) = \min(d'(s, u), \operatorname{Dist}(s, v) + \ell(v, u))$ **Problem:** Find shortest path from *a* to *b*

Program on M_2 (Blind luck):

```
Initialize path = []
path += a
While(notatb)
    take an outgoing edge (u, v) from current node u to v
    current = v
    path += v
return path
```

Does luck allow us to solve unsolvable problems? Consider two machines: M_1 and M_2

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Question:

Does luck allow us to solve unsolvable problems? Consider two machines: M_1 and M_2

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Question: Are there problems which M_2 can solve that M_1 cannot.

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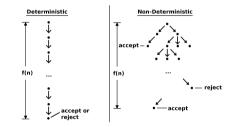
Question: Are there problems which M_2 can solve that M_1 cannot.

The notion was first posed by Robert W. Floyd in 1967.

In computer science, a nondeterministic machine is a theoretical device that can have more than one output for the same input.

A machine that is capable of taking multiple states concurrently. Whenever it reaches a choice, it takes both paths.

If there is a path for the string to be accepted by the machine, then the string is part of the language.



Placeholder slide for youtube.

Why non-determinism?

- Non-determinism adds power to the model; richer programming language and hence (much) easier to "design" programs
- Fundamental in **theory** to prove many theorems
- Very important in **practice** directly and indirectly
- Many deep connections to various fields in Computer Science and Mathematics

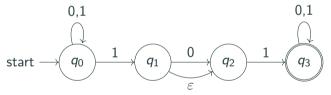
Many interpretations of non-determinism. Hard to understand at the outset. Get used to it and then you will appreciate it slowly.

Non-deterministic finite automata (NFA) Introduction

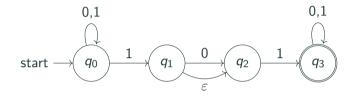
When you come to a fork in the road, take it.

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Today we'll talk about automata whose logic is not deterministic.

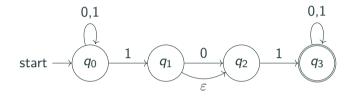


NFA acceptance: Informal



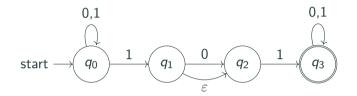
Informal definition: An NFA N accepts a string w iff some accepting state is reached by N from the start state on input w.

NFA acceptance: Informal



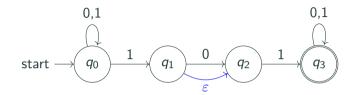
Informal definition: An NFA N accepts a string w iff some accepting state is reached by N from the start state on input w.

The language accepted (or recognized) by a NFA N is denote by L(N) and defined as: $L(N) = \{w \mid N \text{ accepts } w\}.$



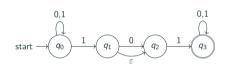
• Is 010110 accepted?

NFA acceptance: Wait! what about the ϵ ?!

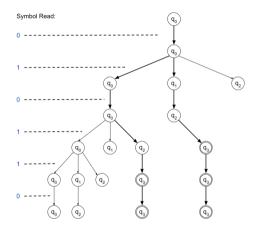


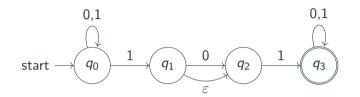
start
$$\rightarrow q_0$$
 $\xrightarrow{1} q_1$ $\xrightarrow{0} q_2$ $\xrightarrow{1} q_3$

Is 010110 accepted?

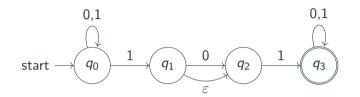


Is 010110 accepted?

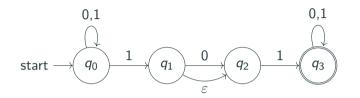




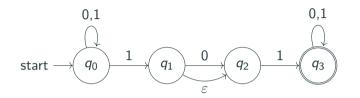
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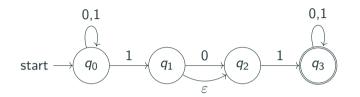
- Is 010110 accepted?
- Is 010 accepted?



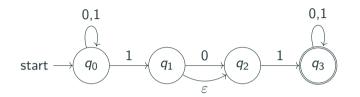
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- Is 10011 accepted?

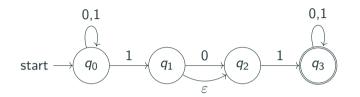


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NFA acceptance: Example



- Is 010110 accepted?
- Is 010 accepted?
- Is 101 accepted?
- Is 10011 accepted?
- What is the language accepted by N?

Comment: Unlike DFAs, it is easier in NFAs to show that a string is accepted than to show that a string is **not** accepted.

Formal definition of NFA

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 $\mathcal{P}(Q)$?

Q: a set. Power set of Q is: $\mathcal{P}(Q) = 2^Q = \{X \mid X \subseteq Q\}$ is set of all subsets of Q.

Example $Q = \{1, 2, 3, 4\}$

$$\mathcal{P}(Q) = \left\{ \begin{array}{c} \{1,2,3,4\}, \\ \{2,3,4\}, \{1,3,4\}, \{1,2,4\}, \{1,2,3\}, \\ \{1,2\}, \{1,3\}, \{1,4\}, \{2,3\}, \{2,4\}, \{3,4\}, \\ \{1\}, \{2\}, \{3\}, \{4\}, \\ \{\} \end{array} \right.$$

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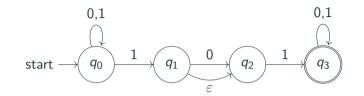
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- $s \in Q$ is the start state,
- A ⊆ Q is the set of accepting/final states.

 $\delta(q, a)$ for $a \in \Sigma \cup \{\varepsilon\}$ is a subset of Q — a set of states.



- *Q* =
- Σ =
- $\delta =$

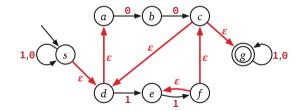
• NFA
$$N = (Q, \Sigma, \delta, s, A)$$

- NFA $N = (Q, \Sigma, \delta, s, A)$
- δ(q, a): set of states that N can go to from q on reading a ∈ Σ ∪ {ε}.

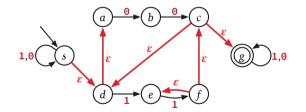
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- $\delta^*(q, w)$: set of states reachable on input w starting in state q.

For NFA $N = (Q, \Sigma, \delta, s, A)$ and $q \in Q$ the ϵ reach(q) is the set of all states that q can reach using only ϵ -transitions.



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Definition For $X \subseteq Q$: ϵ reach $(X) = \bigcup_{x \in X} \epsilon$ reach(x). ϵ reach(q): set of all states that q can reach using only ε -transitions.

Definition

Inductive definition of $\delta^* : Q \times \Sigma^* \to \mathcal{P}(Q)$:

• if $w = \varepsilon$, $\delta^*(q, w) = \epsilon \operatorname{reach}(q)$

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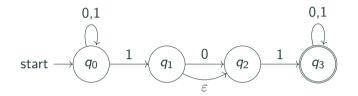
• if
$$w = \varepsilon$$
, $\delta^*(q, w) = \epsilon \operatorname{reach}(q)$

• if
$$w = a$$
 where $a \in \Sigma$: $\delta^*(q, a) = \epsilon \operatorname{reach}\left(\bigcup_{p \in \epsilon \operatorname{reach}(q)} \delta(p, a)\right)$

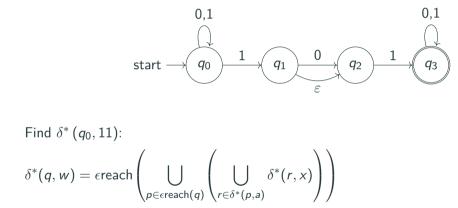
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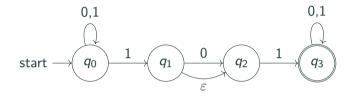
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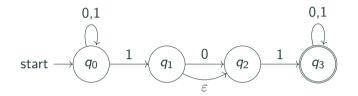


Find $\delta^*(q_0, 11)$:



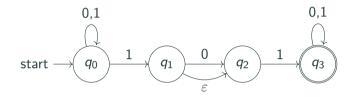


We know
$$w = 11 = ax$$
 so $a = 1$ and $x = 1$
 $\delta^*(q_0, 11) = \epsilon \operatorname{reach}\left(\bigcup_{p \in \epsilon \operatorname{reach}(q_0)} \left(\bigcup_{r \in \delta^*(p, 1)} \delta^*(r, 1)\right)\right)$



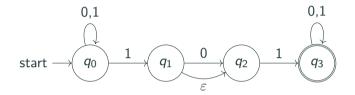
$$\epsilon \operatorname{\mathsf{reach}}(q_0) = \{q_0\}$$

 $\delta^*(q_0, \mathbf{11}) = \epsilon \operatorname{\mathsf{reach}}\left(\bigcup_{p \in \{q_0\}} \left(\bigcup_{r \in \delta^*(p, \mathbf{1})} \delta^*(r, \mathbf{1})\right)\right)$



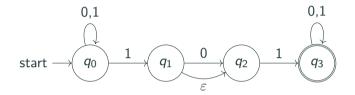
Simplify:

$$\delta^*(q_0, \mathbf{11}) = \epsilon \operatorname{reach}\left(\bigcup_{r \in \delta^*(\{q_0\}, \mathbf{1})} \delta^*(r, \mathbf{1})\right)$$



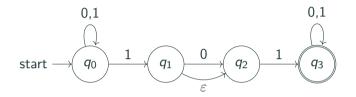
Need
$$\delta^*(q_0, 1) = \epsilon \operatorname{reach}\left(\bigcup_{p \in \epsilon \operatorname{reach}(q)} \delta(p, a)\right) = \epsilon \operatorname{reach}(\delta(q_0, 1)):$$

= $\epsilon \operatorname{reach}(\{q_0, q_1\}) = \{q_0, q_1, q_2\}$
 $\delta^*(q_0, 11) = \epsilon \operatorname{reach}\left(\bigcup_{r \in \delta^*(\{q_0\}, 1)} \delta^*(r, 1)\right)$



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$$\delta^*(q_0, 1) = \epsilon \operatorname{reach}\left(\bigcup_{p \in \epsilon \operatorname{reach}(q)} \delta(p, a)\right) = \epsilon \operatorname{reach}(\delta(q_0, 1)):$$

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 $\delta^*(q_0, 11) = \epsilon \operatorname{reach}\left(\bigcup_{r \in \{q_0, q_1, q_2\}} \delta^*(r, 1)\right)$



Simplify

 $\delta^*(q_0, \mathbf{11}) = \epsilon \mathsf{reach}(\delta^*(q_0, \mathbf{1}) \cup \delta^*(q_1, \mathbf{1}) \cup \delta^*(q_2, \mathbf{1}))$

$$\delta^*(q, w) = \epsilon \operatorname{reach}\left(\bigcup_{p \in \epsilon \operatorname{reach}(q)} \left(\bigcup_{r \in \delta^*(p, a)} \delta^*(r, x)\right)\right)$$

•
$$R = \epsilon \operatorname{reach}(q) \implies \delta^*(q, w) = \epsilon \operatorname{reach}\left(\bigcup_{p \in R} \bigcup_{r \in \delta^*(p, a)} \delta^*(r, x)\right)$$

• $N = \bigcup_{p \in R} \delta^*(p, a)$: All the states reachable from q with the letter a.

•
$$\delta^*(q, w) = \epsilon \operatorname{reach}\left(\bigcup_{r \in N} \delta^*(r, x)\right)$$

A string w is accepted by NFA N if $\delta_N^*(s, w) \cap A \neq \emptyset$.

Definition

The language L(N) accepted by a NFA $N = (Q, \Sigma, \delta, s, A)$ is

 $\{w \in \Sigma^* \mid \delta^*(s, w) \cap A \neq \emptyset\}.$

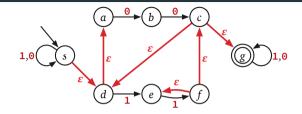
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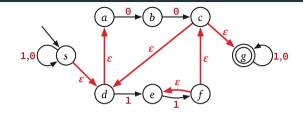
 $\{w \in \Sigma^* \mid \delta^*(s, w) \cap A \neq \emptyset\}.$

Important: Formal definition of the language of NFA above uses δ^* and not δ . As such, one does not need to include ε -transitions closure when specifying δ , since δ^* takes care of that.



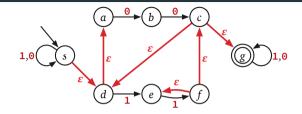
What is:

• $\delta^*(s,\epsilon) =$



What is:

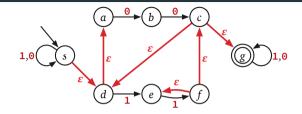
- $\delta^*(s,\epsilon) =$
- $\delta^*(s,0) =$



What is:

- $\delta^*(s,\epsilon) =$
- $\delta^*(s,0) =$
- $\delta^*(b,0) =$

Example



What is:

- $\delta^*(s,\epsilon) =$
- $\delta^*(s,0) =$
- $\delta^*(b,0) =$
- $\delta^*(b,00) =$

Constructing generalized NFAs

- Every DFA is a NFA so NFAs are at least as powerful as DFAs.
- NFAs prove ability to "guess and verify" which simplifies design and reduces number of states
- Easy proofs of some closure properties

 $L = \{$ bitstrings that have a 1 three positions from the end $\}$

For every NFA N there is another NFA N' such that L(N) = L(N') and such that N' has the following two properties:

- N' has single final state f that has no outgoing transitions
- The start state s of N is different from f

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Why couldn't we say this for DFA's?

A simple transformation

Hint: Consider the $L = 0^* + 1^*$.

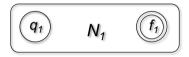
Closure Properties of NFAs

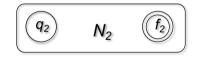
Are the class of languages accepted by NFAs closed under the following operations?

- union
- intersection
- concatenation
- Kleene star
- complement

For any two NFAs N_1 and N_2 there is a NFA N such that $L(N) = L(N_1) \cup L(N_2)$.

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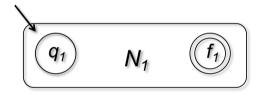


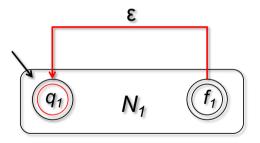


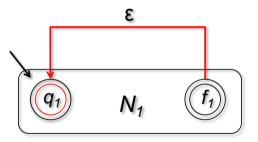
For any two NFAs N_1 and N_2 there is a NFA N such that $L(N) = L(N_1) \cdot L(N_2)$.

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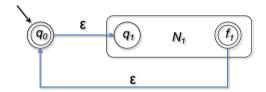








Does not work! Why?



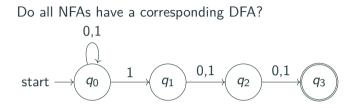
All these examples are examples of language transformations.

A language transformation is one where you take one class or languages, perform some operation and get a new language **that belongs to that same class (closure)**.

Tomorrow's lab will go over more examples of language transformations.

Last thought

Equivalence



Equivalence

