## Pre-lecture brain teaser

You have a graph $\underline{G}(V, E)$. Some of the edges are red, some are white and some are blue. You are given two distinct vertices $u$ and $v$ and want to find a walk $[u \rightarrow v$ ] such that:

- a white edge must be taken after a red edge only.
- a blue edge must be taken after a white edge only.
- and a red edge may be taken after a blue edge only.
- must start on red edge


Develop a algorithm to find a path with these edge constrints.

# ECE-374-B: Lecture 18 - Bellman-Ford and Dynamic Programming on Graphs 

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## Pre-lecture brain teaser



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## Shortest Paths with Negative Length

 EdgesWhy Dijkstra's algorithm fails with negative edges

## Single-Source Shortest Paths with Negative Edge Lengths

Single-Source Shortest Path
Problems
Input: A directed graph
$G=(V, E)$ with arbitrary
(including negative) edge
lengths. For edge $e=(u, v)$, $\ell(e)=\ell(u, v)$ is its length.

- Given nodes s, t find shortest path from s to $t$.

- Given node s find shortest path from s to all other nodes.


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- Given nodes s, t find shortest path from $s$ to $t$.

- Given node s find shortest path from s to all other nodes.


## What are the distances computed by Dijkstra's algorithm?

The distance as computed by Dijkstra algorithm starting from s:

1. $S=0, x=5, y=1$, $z=0$.
2. $s=0, x=1, y=2$, $z=5$.
3. $s=0, x=5, y=1$, $z=2$.
4. IDK.

## Dijkstra's Algorithm and Negative Lengths

With negative length edges, Dijkstra's algorithm can fail


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False assumption: Dijkstra's algorithm is based on the assumption that if $s \rightarrow v_{0} \rightarrow v_{1} \rightarrow v_{2} \ldots \rightarrow v_{k}$ is a shortest path from $s$ to $v_{k}$ then $\operatorname{dist}\left(s, v_{i}\right) \leq \operatorname{dist}\left(s, v_{i+1}\right)$ for $0 \leq i<k$. Holds true only for non-negative edge lengths.

## Shortest Paths with Negative Lengths

## Lemma

Let $G$ be a directed graph with arbitrary edge lengths. If $s=v_{0} \rightarrow v_{1} \rightarrow v_{2} \rightarrow \ldots \rightarrow v_{k}$ is a shortest path from $s$ to $v_{k}$ then for $1 \leq i<k$ :

- $s=v_{0} \rightarrow v_{1} \rightarrow v_{2} \rightarrow \ldots \rightarrow v_{i}$ is a shortest path from $s$ to $v_{i}$


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- $s=v_{0} \rightarrow v_{1} \rightarrow v_{2} \rightarrow \ldots \rightarrow v_{i}$ is a shortest path from $s$ to $v_{i}$
- False: $\operatorname{dist}\left(s, v_{i}\right) \leq \operatorname{dist}\left(s, v_{k}\right)$ for $1 \leq i<k$. Holds true only for non-negative edge lengths.


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- $s=v_{0} \rightarrow v_{1} \rightarrow v_{2} \rightarrow \ldots \rightarrow v_{i}$ is a shortest path from $s$ to $v_{i}$
- False: $\operatorname{dist}\left(s, v_{i}\right) \leq \operatorname{dist}\left(s, v_{k}\right)$ for $1 \leq i<k$. Holds true only for non-negative edge lengths.

Cannot explore nodes in increasing order of distance! We need other strategies.

Why can't we just re-normalize the edge lengths!?

## Instinctual thought

Why can't we simply add a weight to each edge so that the shortest length is 0 (or positive).


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Shortest Path: $s \rightarrow a \rightarrow c \rightarrow t$


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## Instinctual thought

Why can't we simply add a weight to each edge so that the shortest length is 0 (or positive).


Shortest Path: $s \rightarrow a \rightarrow c \rightarrow t$


Shortest Path: $s \rightarrow b \rightarrow t$ Adding weights to edges penalizes paths with more edges.

## But wait! Things get worse: Negative cycles

## Negative Length Cycles

## Definition

A cycle $C$ is a negative length cycle if the sum of the edge lengths of $C$ is negative.


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A cycle $C$ is a negative length cycle if the sum of the edge lengths of $C$ is negative.


What is the shortest path distance between $s$ and $t$ ?
Reminder: Paths have to be simple...

## Shortest Paths and Negative Cycles

Given $G=(V, E)$ with edge lengths and $s, t$. Suppose

- $G$ has a negative length cycle $C$, and
- s can reach $C$ and $C$ can reach $t$.


## Shortest Paths and Negative Cycles

Given $G=(V, E)$ with edge lengths and $s, t$. Suppose

- $G$ has a negative length cycle $C$, and
- s can reach $C$ and $C$ can reach $t$.

Question: What is the shortest distance from s to $t$ ?
Possible answers: Define shortest distance to be:

- undefined, that is $-\infty$, OR
- the length of a shortest simple path from $s$ to $t$.


## Really bad new about negative edges, and shortest path...

## Lemma

If there is an efficient algorithm to find a shortest simple $s \rightarrow t$ path in a graph with negative edge lengths, then there is an efficient algorithm to find the longest simple $s \rightarrow t$ path in a graph with positive edge lengths.

Finding the $s \rightarrow t$ longest path is difficult. NP-HARD!

## Restating problem of Shortest path with negative edges

## Alternatively: Finding Shortest Walks

Given a graph $G=(V, E)$ :

- A path is a sequence of distinct vertices $v_{1}, v_{2}, \ldots, v_{k}$ such that $\left(v_{i}, v_{i+1}\right) \in E$ for $1 \leq i \leq k-1$.
- A walk is a sequence of vertices $v_{1}, v_{2}, \ldots, v_{k}$ such that $\left(v_{i}, v_{i+1}\right) \in E$ for $1 \leq i \leq k-1$. Vertices are allowed to repeat.

Define $\operatorname{dist}(u, v)$ to be the length of a shortest walk from $u$ to $v$.

- If there is a walk from $u$ to $v$ that contains negative length cycle then $\operatorname{dist}(u, v)=-\infty$
- Else there is a path with at most $n-1$ edges whose length is equal to the length of a shortest walk and $\operatorname{dist}(u, v)$ is finite

Helpful to think about walks

## Shortest Paths with Negative Edge Lengths - Problems

Algorithmic Problems
Input: A directed graph $G=(V, E)$ with edge lengths (could be negative). For edge $e=(u, v), \ell(e)=\ell(u, v)$ is its length.

## Questions:

- Given nodes $s, t$, either find a negative length cycle $C$ that $s$ can reach or find a shortest path from $s$ to $t$.
- Given node s, either find a negative length cycle $C$ that s can reach or find shortest path distances from s to all reachable nodes.
- Check if $G$ has a negative length cycle or not.


## Shortest Paths with Negative Edge Lengths - In Undirected Graphs

Note: With negative lengths, shortest path problems and negative cycle detection in undirected graphs cannot be reduced to directed graphs by bi-directing each undirected edge. Why?

Problem can be solved efficiently in undirected graphs but algorithms are different and significantly more involved than those for directed graphs. One need to compute $T$-joins in the relevant graph. Pretty painful stuff.

## Bellman Ford Algorithm

Shortest path via number of hops

## Shortest Paths and Recursion

- Compute the shortest path distance from s to $t$ recursively?
-What are the smaller sub-problems?


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- $s=v_{0} \rightarrow v_{1} \rightarrow v_{2} \rightarrow \ldots \rightarrow v_{i}$ is a shortest path from $s$ to $v_{i}$


## Shortest Paths and Recursion

- Compute the shortest path distance from s to $t$ recursively?
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Let $G$ be a directed graph with arbitrary edge lengths. If
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Sub-problem idea: paths of fewer hops/edges

## Hop-based Recursion: Bellman-Ford Algorithm

Single-source problem: fix source s.
Assume that all nodes can be reached by s in G Assume $G$ has no negative-length cycle (for now).
$d(v, k)$ : shortest walk length from $s$ to $v$ using at most $k$ edges.

## Hop-based Recursion: Bellman-Ford Algorithm

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Note: $\operatorname{dist}(s, v)=d(v, n-1)$.

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$d(v, k)$ : shortest walk length from $s$ to $v$ using at most $k$ edges.
Note: $\operatorname{dist}(s, v)=d(v, n-1)$. Recursion for $d(v, k)$ :

$$
d(v, k)=\min \left\{\begin{array}{l}
\min _{u \in V}(d(u, k-1)+\ell(u, v)) \\
d(v, k-1)
\end{array}\right.
$$

Base case: $d(s, 0)=0$ and $d(v, 0)=\infty$ for all $v \neq s$.

## Example



## Example

|  | round | s | a | b | c | d | e | f |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| -8, 2 | 0 | 0 | $\infty$ | $\infty$ | $\infty$ | $\infty$ | $\infty$ | $\infty$ |
| $d \infty<1-\infty f$ |  |  |  |  |  |  |  |  |
| $-3 \quad 0 \quad 5 \quad-3$ |  |  |  |  |  |  |  |  |
| 8 - -1 |  |  |  |  |  |  |  |  |
| $a \dot{\infty} \quad 4 \quad c$ |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |
| $0 s^{3}$ |  |  |  |  |  |  |  |  |

## Example

c|c|c|c|c|c|c|c|c|c|

## Example

(4)

## Example

(2):

## Example

|  | round | S | a | b | C | d | e | f |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| -8 2 | 0 | 0 | $\infty$ | $\infty$ | $\infty$ | $\infty$ | $\infty$ | $\infty$ |
| $d(2) 1$ (7) $f$ | 1 | 0 | 6 | 4 | 3 | $\infty$ | $\infty$ | $\infty$ |
| $\begin{array}{llll} -3 & 0 & 5 \\ -3 \end{array}$ | 2 | 0 | 6 | 2 | 3 | 4 | $\infty$ | 9 |
| 8. -1 | 3 | 0 | 1 | 2 | 3 | 2 | 11 | 7 |
| a) 4 (1) $c$ | 4 | 0 | -1 | 2 | 3 | 2 | 9 | 7 |
| 6 |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |

## Example



## Example

(

## Example

(

The Bellman-Ford Algorithm

## Bellman-Ford Algorithm

$$
\begin{aligned}
& \text { Create in(G) list from } \operatorname{adj}(G) \\
& \text { for each } u \in V \text { do } \\
& \qquad \begin{array}{c}
d(u, 0) \leftarrow \infty \\
d(s, 0) \leftarrow 0
\end{array} \\
& \text { for } k=1 \text { to } n-1 \text { do } \\
& \text { for each } v \in V \text { do } \\
& \quad d(v, k) \leftarrow d(v, k-1) \\
& \text { for each edge }(u, v) \in \operatorname{in}(v) \text { do } \\
& \quad d(v, k)=\min \{d(v, k), d(u, k-1)+\ell(u, v)\}
\end{aligned}
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for each $v \in V$ do

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Running time:

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Running time: $O(n(n+m))$

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Running time: $O(n(n+m))$ Space:

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Running time: $O(n(n+m))$ Space: $O\left(m+n^{2}\right)$

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Running time: $O(n(n+m))$ Space: $O\left(m+n^{2}\right)$
Space can be reduced to $O(m+n)$.

## Bellman-Ford Algorithm: Cleaner version

$$
\begin{aligned}
& \text { for each } u \in V \text { do } \\
& \quad d(u) \leftarrow \infty \\
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& \text { for } k=1 \text { to } n-1 \text { do } \\
& \text { for each } v \in V \text { do } \\
& \text { for each edge }(u, v) \in \operatorname{in}(v) \text { do } \\
& \quad d(v)=\min \{d(v), d(u)+\ell(u, v)\}
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for each $v \in V$ do

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Running time: $O(m n)$ Space: $O(m+n)$

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for each $v \in V$ do

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Running time: $O(m n)$ Space: $O(m+n)$ Do we need the in $(\mathrm{V})$ list?

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for each $v \in V$ do

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Running time: $O(m n)$ Space: $O(n)$
Do we need the in(V) list?

## Bellman-Ford: Detecting negative cycles

## Negative cycles

What happens if we run this on a graph with negative cycles?


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## Correctness: detecting negative length cycle

## Lemma

Suppose $G$ has a negative cycle $C$ reachable from s. Then there is some node $v \in C$ such that $d(v, n)<d(v, n-1)$.

## Correctness: detecting negative length cycle

## Lemma

Suppose $G$ has a negative cycle $C$ reachable from s. Then there is some node $v \in C$ such that $d(v, n)<d(v, n-1)$.

## Proof.

Suppose not. Let $C=v_{1} \rightarrow v_{2} \rightarrow \ldots \rightarrow v_{h} \rightarrow v_{1}$ be negative length cycle reachable from s. $d\left(v_{i}, n-1\right)$ is finite for $1 \leq i \leq h$ since $C$ is reachable from $s$. By assumption $d(v, n) \geq d(v, n-1)$ for all $v \in C$; implies no change in $n^{\text {th }}$ iteration; $d\left(v_{i}, n-1\right)=d\left(v_{i}, n\right)$ for $1 \leq i \leq h$. This means $d\left(v_{i}, n-1\right) \leq d\left(v_{i-1}, n-1\right)+\ell\left(v_{i-1}, v_{i}\right)$ for $2 \leq i \leq h$ and $d\left(v_{1}, n-1\right) \leq d\left(v_{n}, n-1\right)+\ell\left(v_{n}, v_{1}\right)$. Adding up all these inequalities results in the inequality $0 \leq \ell(C)$ which contradicts the assumption that $\ell(C)<0$.

## Proof of Lemma in more detail...

$$
\begin{aligned}
& d\left(v_{1}, n\right) \leq d\left(v_{0}, n-1\right)+\ell\left(v_{0}, v_{1}\right) \\
& d\left(v_{2}, n\right) \leq d\left(v_{1}, n-1\right)+\ell\left(v_{1}, v_{2}\right) \\
& \cdots
\end{aligned}
$$

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& \ldots \\
&{ }_{3}^{3} d\left(v_{i}, n\right) \leq d\left(v_{i-1}, n\right)+\ell\left(v_{i-1}, v_{i}\right) \\
& \ldots \\
& d\left(v_{k}, n\right) \leq d\left(v_{k-1}, n\right)+\ell\left(v_{k-1}, v_{k}\right) \\
& d\left(v_{0}, n\right) \leq d\left(v_{k}, n\right)+\ell\left(v_{k}, v_{0}\right)
\end{aligned}
$$

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& \ldots
\end{aligned}
$$

## Proof of Lemma in more detail...

$$
\begin{aligned}
& \sum_{i=0}^{k} d\left(v_{i}, n\right) \leq \sum_{i=0}^{k} d\left(v_{i}, n\right)+\sum_{i=1}^{k} \ell\left(v_{i-1}, v_{i}\right)+\ell\left(v_{k}, v_{0}\right) \\
& 0 \leq \sum_{i=1}^{k} \ell\left(v_{i-1}, v_{i}\right)+\ell\left(v_{k}, v_{0}\right)
\end{aligned}
$$

## Proof of Lemma in more detail...

$$
\begin{aligned}
& \sum_{i=0}^{k} d\left(v_{i}, n\right) \leq \sum_{i=0}^{k} d\left(v_{i}, n\right)+\sum_{i=1}^{k} \ell\left(v_{i-1}, v_{i}\right)+\ell\left(v_{k}, v_{0}\right) \\
& 0 \leq \sum_{i=1}^{k} \ell\left(v_{i-1}, v_{i}\right)+\ell\left(v_{k}, v_{0}\right)=\operatorname{len}(C)
\end{aligned}
$$

## Proof of Lemma in more detail...

$$
\begin{aligned}
& \sum_{i=0}^{k} d\left(v_{i}, n\right) \leq \sum_{i=0}^{k} d\left(v_{i}, n\right)+\sum_{i=1}^{k} \ell\left(v_{i-1}, v_{i}\right)+\ell\left(v_{k}, v_{0}\right) \\
& 0 \leq \sum_{i=1}^{k} \ell\left(v_{i-1}, v_{i}\right)+\ell\left(v_{k}, v_{0}\right)=\operatorname{len}(C) .
\end{aligned}
$$

$C$ is a not a negative cycle. Contradiction.

## Negative cycles can not hide

## Lemma restated

If $G$ does not has a negative length cycle reachable from $s \Longrightarrow$ $\forall v: d(v, n)=d(v, n-1)$.

Also, $d(v, n-1)$ is the length of the shortest path between $s$ and $v$.

Put together are the following:
Lemma
$G$ has a negative length cycle reachable from $s \Longleftrightarrow$ there is some node $v$ such that $d(v, n)<d(v, n-1)$.

## Bellman-Ford: Negative Cycle Detection - final version

```
for each }u\inV\mathrm{ do
    d(u)\leftarrow\infty
d(s)}\leftarrow
for }k=1\mathrm{ to }n-1\mathrm{ do
    for each v}\inV\mathrm{ do
        for each edge (u,v)\inin(v) do
        d(v)}=\operatorname{min}{d(v),d(u)+\ell(u,v)
(* One more iteration to check if distances change *)
for each v\inV do
    for each edge (u,v)\inin(v) do
        if }(d(v)>d(u)+\ell(u,v)
            Output '`Negative Cycle''
for each }v\inV\mathrm{ do
    dist}(s,v)\leftarrowd(v
```


## Variants on Bellman-Ford

## Finding the Paths and a Shortest Path Tree

How do we find a shortest path tree in addition to distances?

- For each $v$ the $d(v)$ can only get smaller as algorithm proceeds.
- If $d(v)$ becomes smaller it is because we found a vertex $u$ such that $d(v)>d(u)+\ell(u, v)$ and we update $d(v)=d(u)+\ell(u, v)$. That is, we found a shorter path to $v$ through $u$.
- For each $v$ have a $\operatorname{prev}(v)$ pointer and update it to point to $u$ if $v$ finds a shorter path via $u$.
- At end of algorithm $\operatorname{prev}(v)$ pointers give a shortest path tree oriented towards the source s.


## Negative Cycle Detection

Negative Cycle Detection
Given directed graph $G$ with arbitrary edge lengths, does it have a negative length cycle?

## Negative Cycle Detection

## Negative Cycle Detection

Given directed graph G with arbitrary edge lengths, does it have a negative length cycle?

- Bellman-Ford checks whether there is a negative cycle C that is reachable from a specific vertex s. There may negative cycles not reachable from s.
- Run Bellman-Ford $|V|$ times, once from each node $u$ ?


## Negative Cycle Detection

- Add a new node $s^{\prime}$ and connect it to all nodes of $G$ with zero length edges. Bellman-Ford from $s^{\prime}$ will fill find a negative length cycle if there is one. Exercise: why does this work?
- Negative cycle detection can be done with one Bellman-Ford invocation.

Shortest Paths in DAGs

## Shortest Paths in a DAG

Single-Source Shortest Path Problems
Input A directed acyclic graph $G=(V, E)$ with arbitrary (including negative) edge lengths. For edge $e=(u, v), \ell(e)=\ell(u, v)$ is its length.

- Given nodes $s, t$ find shortest path from $s$ to $t$.
- Given node s find shortest path from s to all other nodes.


## Shortest Paths in a DAG

Single-Source Shortest Path Problems
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- Given nodes $s, t$ find shortest path from $s$ to $t$.
- Given node s find shortest path from s to all other nodes.

Simplification of algorithms for DAGs

- No cycles and hence no negative length cycles! Hence can find shortest paths even for negative length edges
- Can order nodes using topological sort


## Algorithm for DAGs

- Want to find shortest paths from s. Ignore nodes not reachable from $s$.
- Let $S=v_{1}, v_{2}, v_{i+1}, \ldots, v_{n}$ be a topological sort of $G$


## Algorithm for DAGs

- Want to find shortest paths from s. Ignore nodes not reachable from s.
- Let $s=v_{1}, v_{2}, v_{i+1}, \ldots, v_{n}$ be a topological sort of $G$

Observation:

- shortest path from $s$ to $v_{i}$ cannot use any node from $v_{i+1}, \ldots, v_{n}$
- can find shortest paths in topological sort order.


## Shortest Paths for DAGs - Example



## Shortest Paths for DAGs - Example



## Algorithm for DAGs

$$
\begin{aligned}
& \text { for } i=1 \text { to } n \text { do } \\
& \qquad d\left(s, v_{i}\right)=\infty \\
& d(s, s)=0 \\
& \text { for } i=1 \text { to } n-1 \text { do } \\
& \quad \text { for each edge }\left(v_{i}, v_{j}\right) \text { in } \operatorname{Adj}\left(v_{i}\right) \text { do } \\
& \qquad d\left(s, v_{j}\right)=\min \left\{d\left(s, v_{j}\right), d\left(s, v_{i}\right)+\ell\left(v_{i}, v_{j}\right)\right\} \\
& \text { return } d(s, \cdot) \text { values computed }
\end{aligned}
$$

Correctness: induction on $i$ and observation in previous slide. Running time: $O(m+n)$ time algorithm! Works for negative edge lengths and hence can find longest paths in a DAG.

All Pairs Shortest Paths

## Shortest Path Problems

## Shortest Path Problems

$$
\begin{aligned}
& \text { Input } A \text { (undirected or directed) graph } G=(V, E) \text { with } \\
& \text { edge lengths (or costs). For edge } e=(u, v) \text {, } \\
& \ell(e)=\ell(u, v) \text { is its length. }
\end{aligned}
$$

- Given nodes $s, t$ find shortest path from $s$ to $t$.
- Given node s find shortest path from s to all other nodes.
- Find shortest paths for all pairs of nodes.


## SSSP: Single-Source Shortest Paths

Single-Source Shortest Path Problems
Input A (undirected or directed) graph $G=(V, E)$ with edge lengths. For edge $e=(u, v), \ell(e)=\ell(u, v)$ is its length.

- Given nodes $s, t$ find shortest path from $s$ to $t$.
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## SSSP: Single-Source Shortest Paths

Single-Source Shortest Path Problems
Input A (undirected or directed) graph $G=(V, E)$ with edge lengths. For edge $e=(u, v), \ell(e)=\ell(u, v)$ is its length.

- Given nodes $s, t$ find shortest path from $s$ to $t$.
- Given node s find shortest path from s to all other nodes.

Dijkstra's algorithm for non-negative edge lengths. Running time: $O((m+n) \log n)$ with heaps and $O(m+n \log n)$ with advanced priority queues.
Bellman-Ford algorithm for arbitrary edge lengths. Running time: $O(n m)$.

## All-Pairs Shortest Paths - Using known algorithms...

All-Pairs Shortest Path Problem
Input A (undirected or directed) graph $G=(V, E)$ with edge lengths. For edge $e=(u, v), \ell(e)=\ell(u, v)$ is its length.

- Find shortest paths for all pairs of nodes.


## All-Pairs Shortest Paths - Using known algorithms...

All-Pairs Shortest Path Problem
Input A (undirected or directed) graph $G=(V, E)$ with edge lengths. For edge $e=(u, v), \ell(e)=\ell(u, v)$ is its length.

- Find shortest paths for all pairs of nodes.

Apply single-source algorithms $n$ times, once for each vertex.

- Non-negative lengths. $O(n m \log n)$ with heaps and $O\left(n m+n^{2} \log n\right)$ using advanced priority queues.
- Arbitrary edge lengths: $O\left(n^{2} m\right)$.
$\Theta\left(n^{4}\right)$ if $m=\Omega\left(n^{2}\right)$.


## All-Pairs Shortest Paths - Using known algorithms...

All-Pairs Shortest Path Problem
Input A (undirected or directed) graph $G=(V, E)$ with edge lengths. For edge $e=(u, v), \ell(e)=\ell(u, v)$ is its length.

- Find shortest paths for all pairs of nodes.

Apply single-source algorithms $n$ times, once for each vertex.

- Non-negative lengths. $O(n m \log n)$ with heaps and $O\left(n m+n^{2} \log n\right)$ using advanced priority queues.
- Arbitrary edge lengths: $O\left(n^{2} m\right)$.

$$
\Theta\left(n^{4}\right) \text { if } m=\Omega\left(n^{2}\right)
$$

Can we do better?

## All Pairs Shortest Paths: A recursive solution

## All-Pairs: Recursion on index of intermediate nodes

- Number vertices arbitrarily as $v_{1}, v_{2}, \ldots, v_{n}$
- dist( $i, j, k)$ : length of shortest walk from $v_{i}$ to $v_{j}$ among all walks in which the largest index of an intermediate node is at most $k$ (could be $-\infty$ if there is a negative length cycle).



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- Number vertices arbitrarily as $v_{1}, v_{2}, \ldots, v_{n}$
- dist( $i, j, k)$ : length of shortest walk from $v_{i}$ to $v_{j}$ among all walks in which the largest index of an intermediate node is at most $k$ (could be $-\infty$ if there is a negative length cycle).


For the following graph, $\operatorname{dist(}(\mathrm{i}, \mathrm{j}, 2)$ is...


1. 9
2. 10
3. 11
4. 12
5. 15

## All-Pairs: Recursion on index of intermediate nodes



$$
\operatorname{dist}(i, j, k)=\min \left\{\begin{array}{l}
\operatorname{dist}(i, j, k-1) \\
\operatorname{dist}(i, k, k-1)+\operatorname{dist}(k, j, k-1)
\end{array}\right.
$$

Base case: $\operatorname{dist}(i, j, 0)=\ell(i, j)$ if $(i, j) \in E$, otherwise $\infty$
Correctness: If $i \rightarrow j$ shortest walk goes through $k$ then $k$ occurs only once on the path - otherwise there is a negative length

## All-Pairs: Recursion on index of intermediate nodes

If $i$ can reach $k$ and $k$ can reach $j$ and $\operatorname{dist}(k, k, k-1)<0$ then $G$ has a negative length cycle containing $k$ and $\operatorname{dist}(i, j, k)=-\infty$.

Recursion below is valid only if $\operatorname{dist}(k, k, k-1) \geq 0$. We can detect this during the algorithm or wait till the end.

$$
\operatorname{dist}(i, j, k)=\min \left\{\begin{array}{l}
\operatorname{dist}(i, j, k-1) \\
\operatorname{dist}(i, k, k-1)+\operatorname{dist}(k, j, k-1)
\end{array}\right.
$$

Floyd-Warshall algorithm

## Floyd-Warshall Algorithm - for All-Pairs Shortest Paths

$$
d(i, j, k)=\min \left\{\begin{array}{l}
d(i, j, k-1) \\
d(i, k, k-1)+d(k, j, k-1)
\end{array}\right.
$$

$$
\begin{aligned}
& \text { for } \begin{array}{l}
i=1 \text { to } n \text { do } \\
\text { for } j=1 \text { to } n \text { do } \\
\quad d(i, j, 0)=\ell(i, j)
\end{array} \\
& \begin{array}{r}
\text { for } \ell(i, j)=\infty \text { if }(i, j) \notin E, 0 \text { if } i=j *) \\
\text { for } i=1 \text { to } n \text { do } n \text { do } \\
\text { for } j=1 \text { to } n \text { do } \\
\qquad d(i, j, k)=\min \left\{\begin{array}{l}
d(i, j, k-1), \\
d(i, k, k-1)+d(k, j, k-1)
\end{array}\right. \\
\text { for } i=1 \text { to } n \text { do } \\
\quad \text { if (dist }(i, i, n)<0) \text { then } \\
\text { Output } \exists \text { negative cycle in } G
\end{array}
\end{aligned}
$$

## Floyd-Warshall Algorithm - for All-Pairs Shortest Paths

$$
d(i, j, k)=\min \left\{\begin{array}{l}
d(i, j, k-1) \\
d(i, k, k-1)+d(k, j, k-1)
\end{array}\right.
$$

$$
\begin{aligned}
& \text { for } \begin{array}{l}
i=1 \text { to } n \text { do } \\
\text { for } j=1 \text { to } n \text { do } \\
\quad d(i, j, 0)=\ell(i, j)
\end{array} \\
& \begin{array}{l}
\text { for } \ell(i, j)=\infty \text { if }(i, j) \notin E, 0 \text { if } i=j *) \\
\text { for } i=1 \text { to } n \text { do do } \\
\text { for } j=1 \text { to } n \text { do } \\
\qquad d(i, j, k)=\min \left\{\begin{array}{l}
d(i, j, k-1), \\
d(i, k, k-1)+d(k, j, k-1)
\end{array}\right. \\
\text { for } i=1 \text { to } n \text { do } \\
\quad \text { if (dist }(i, i, n)<0) \text { then } \\
\quad \text { Output } \exists \text { negative cycle in } G
\end{array}
\end{aligned}
$$

Running Time:

## Floyd-Warshall Algorithm - for All-Pairs Shortest Paths

$$
d(i, j, k)=\min \left\{\begin{array}{l}
d(i, j, k-1) \\
d(i, k, k-1)+d(k, j, k-1)
\end{array}\right.
$$

$$
\begin{aligned}
& \text { for } \begin{array}{l}
i=1 \text { to } n \text { do } \\
\text { for } j=1 \text { to } n \text { do } \\
\quad d(i, j, 0)=\ell(i, j)
\end{array} \\
& \begin{array}{r}
(* \ell(i, j)=\infty \text { if }(i, j) \notin E, 0 \text { if } i=j *) \\
\text { for } k=1 \text { to } n \text { do } \\
\text { for } i=1 \text { to } n \text { do } \\
\text { for } j=1 \text { to } n \text { do } \\
\qquad d(i, j, k)=\min \left\{\begin{array}{l}
d(i, j, k-1), \\
d(i, k, k-1)+d(k, j, k-1)
\end{array}\right. \\
\text { for } i=1 \text { to } n \text { do } \\
\text { if (dist }(i, i, n)<0) \text { then } \\
\text { Output } \exists \text { negative cycle in } G
\end{array}
\end{aligned}
$$

Running Time: $\Theta\left(n^{3}\right)$. Space: $\Theta\left(n^{3}\right)$.

## Floyd-Warshall Algorithm - for All-Pairs Shortest Paths

$$
d(i, j, k)=\min \left\{\begin{array}{l}
d(i, j, k-1) \\
d(i, k, k-1)+d(k, j, k-1)
\end{array}\right.
$$

$$
\begin{aligned}
& \text { for } \begin{array}{l}
i=1 \text { to } n \text { do } \\
\text { for } j=1 \text { to } n \text { do } \\
d(i, j, 0)=\ell(i, j)
\end{array} \\
& \begin{array}{r}
\text { for } \ell(i, j)=\infty \text { if }(i, j) \notin E, 0 \text { if } i=j *) \\
\text { for } i=1 \text { to } n \text { do } n \text { do } \\
\text { for } j=1 \text { to } n \text { do } \\
\qquad d(i, j, k)=\min \left\{\begin{array}{l}
d(i, j, k-1), \\
d(i, k, k-1)+d(k, j, k-1)
\end{array}\right. \\
\text { for } i=1 \text { to } n \text { do } \\
\text { if (dist( } i, i, n)<0) \text { then } \\
\text { Output } \exists \text { negative cycle in } G
\end{array}
\end{aligned}
$$

Running Time: $\Theta\left(n^{3}\right)$. Space: $\Theta\left(n^{3}\right)$.
Correctness: via induction and recursive definition

## Floyd-Warshall Algorithm: Finding the Paths

Question: Can we find the paths in addition to the distances?

## Floyd-Warshall Algorithm: Finding the Paths

Question: Can we find the paths in addition to the distances?

- Create a $n \times n$ array Next that stores the next vertex on shortest path for each pair of vertices
- With array Next, for any pair of given vertices $i, j$ can compute a shortest path in $O(n)$ time.


## Floyd-Warshall Algorithm - Finding the Paths

$$
\begin{aligned}
& \text { for } \begin{array}{l}
i=1 \text { to } n \text { do } \\
\text { for } j=1 \text { to } n \text { do } \\
\quad d(i, j, 0)=\ell(i, j) \\
\begin{array}{c}
\text { (* } \ell(i, j)=\infty \text { if }(i, j) \text { not edge, } 0 \text { if } i=j *) \\
\\
\text { Next }(i, j)=-1
\end{array} \\
\text { for } k=1 \text { to } n \text { do } \\
\text { for } i=1 \text { to } n \text { do } \\
\text { for } j=1 \text { to } n \text { do } \\
\quad \text { if }(d(i, j, k-1)>d(i, k, k-1)+d(k, j, k-1)) \text { then } \\
\quad d(i, j, k)=d(i, k, k-1)+d(k, j, k-1) \\
\quad N e x t(i, j)=k
\end{array} \\
& \text { for } i=1 \text { to } n \text { do } \\
& \text { if ( } d(i, i, n)<0) \text { then } \\
& \quad \text { Output that there is a negative length cycle in } G
\end{aligned}
$$

Exercise: Given Next array and any two vertices $i, j$ describe an $O(n)$ algorithm to find a $i-j$ shortest path.

Summary of shortest path algorithms

## Summary of results on shortest paths

| Single source |  |  |
| :--- | :--- | :--- |
| No negative edges | Dijkstra | $O(n \log n+m)$ |
| Edge lengths can be negative | Bellman Ford | $O(n m)$ |

## All Pairs Shortest Paths

| No negative edges | $n$ * Dijkstra | $O\left(n^{2} \log n+n m\right)$ |
| :--- | :--- | :--- |
| No negative cycles | $n^{*}$ Bellman Ford | $O\left(n^{2} m\right)=O\left(n^{4}\right)$ |
| No negative cycles | Johnson's ${ }^{1}$ | $O\left(n m+n^{2} \log n\right)$ |
| No negative cycles | Floyd-Warshall | $O\left(n^{3}\right)$ |
| Unweighted | Matrix multiplication ${ }^{2}$ | $O\left(n^{2.38}\right), O\left(n^{2.58}\right)$ |

## Summary of results on shortest paths

(1): The algorithm for the case that there are no negative cycles, and doing all shortest paths, works by computing a potential function using Bellman-Ford and then doing Dijkstra. It is mentioned for the sake of completeness, but it outside the scope of the class.
(2): https://resources.mpi-inf.mpg.de/ departments/d1/teaching/ss12/ AdvancedGraphAlgorithms/Slides14.pdf

Fin

