

CS/ECE-374-B: Algorithms and Models of Computation, Spring 2024  
Midterm exam 3 – April 25, 2024

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- You can do hard things! Grades do matter, but not as much as you may think, but then life is uncertain anyway, so what.
  - **Don't cheat.** The consequence for cheating is far greater than the reward. Just try your best and you'll be fine.
  - **Please read the entire exam before writing anything.** There are 6 problems and most have multiple parts.
  - This is a closed-book exam. At the end of the exam, you'll find a multi-page cheat sheet. *Do not tear out the cheat sheet!* No outside material is allowed on this exam.
  - You should write your answers legibly and in the space given for the question. Overly verbose answers will be penalized.
  - Scratch paper is available on the back of the exam. *Do not tear out the scratch paper!* It messes with the auto-scanner.
  - **You have 75 minutes (1.25 hours) for the exam.** Manage your time well. *Do not spend too much time on questions you do not understand and focus on answering as much as you can!*
  - Make sure you *use the time well to think, be precise, and show as much work as possible.*
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Name: \_\_\_\_\_

NetID: \_\_\_\_\_

Date: \_\_\_\_\_

**Problem 1 [10 points]**

For each of the following statements, answer if it is True or False. Use the table at the bottom to mark your choices.

- i. Dijkstra's algorithm works well on graphs with negative edge weights provided there is no negative length cycle.
- ii. A problem can either be NP-Complete or NP-Hard but not both.
- iii. If  $P = NP$  then every NP-Complete problem can be solved in polynomial time.
- iv. Graph 2-Coloring can be decided in linear time.
- v. The set of all programs is larger than the set of all languages.
- vi. Every undecidable language is also unrecognizable.
- vii. If language  $L$  is undecidable then either  $L$  or  $\bar{L}$  is unrecognizable.
- viii. If using an Oracle for problem  $X$ , one can obtain a decider for the  $\text{HalT}_{\text{TM}}$  then  $X$  is decidable.
- ix. If a barber shaves everyone who doesn't shave themselves then the barber shaves themselves.
- x. If a graph is 3-colorable then it has 3 independent sets.

**Table 1.**

Statement	Your choice
i.	
ii.	
iii.	
iv.	
v.	
vi.	
vii.	
viii.	
ix.	
x.	

**Problem 2 [10 points]**

Given a directed graph  $G = (V, E)$  with non-negative edge lengths  $l(e), e \in E$  and a node  $s \in V$ , describe an algorithm to find the length of a shortest cycle containing the node  $s$ .

**Problem 3 [10 points]**

Formally prove or disprove the following statement. *There is no program that always stops and solves the halting problem.*

**Problem 4 [20 points]**

The 4-Set-Packing problem is defined as follows.

- Inputs: A collection of  $m$  sets  $S = \{S_1, S_2, \dots, S_m\}$  such that  $|S_i| = 4 \forall i \in \{1, \dots, m\}$  and an integer  $k$ .
- Output: True if there exists a disjoint subcollection  $L \subseteq S$  of size  $k$ . False otherwise.  
Note: Disjoint subcollection means no individual element belongs to two different sets in it.

The 3-Dimensional-Matching problem is defined as follows.

- Inputs: Three disjoint sets  $X, Y$  and  $Z$  of  $n$  elements each, and a set of triplets  $T \subseteq X \times Y \times Z$ .
- Output: True if there exist disjoint triplets from  $T$  whose union is  $X \cup Y \cup Z$ . False otherwise.

Given 3-Dimensional Matching is NP-Complete, show that 4-Set-Packing is NP-Complete.

**Problem 5 [14 points]**

- a. A quasi-satisfying assignment (quasiSAT) for a 3CNF boolean formula  $\phi$  is an assignment of truth values to the variables such that at most one clause in  $\phi$  does not contain a True literal. Prove that it is NP-Complete to determine whether a given 3CNF boolean formula has a quasi-satisfying assignment or not.

- b. Show that the Hamiltonian Cycle problem for **undirected** graphs is NP-Complete. Note: You may use that Hamiltonian Cycle problem for directed graphs is NP-Complete.

**Problem 6 [10 points]**

Identify the errors in the following proofs.

a. Define the following problems.

- DFA-Accepts

Inputs: A DFA  $D$  and a string  $w$ . Output: True if  $w \in L(D)$ . False otherwise.

- NFA-Accepts

Inputs: A NFA  $N$  and a string  $w$ . Output: True if  $w \in L(N)$ . False otherwise.

Note the following.

- DFA-Accepts is in P as there is a single execution path for  $w$  on  $D$ .
- Its highly unlikely that NFA-Accepts is in P. Intuitively, there are exponentially many ways to simulate  $w$  on  $N$  that makes NFA-Accepts NP-Hard.

Construct a solver for NFA-Accepts as follows.

Step 1. Convert the given NFA into an equivalent DFA.

Step 2. Now use the poly-time solver for DFA-Accepts to solve NFA-Accepts.

This implies NFA-Accepts which is NP-Hard has a poly-time solver implying  $P = NP$ . [Did we just solve the millennium problem!?!]



- b. Refer to the cheat sheet for the definition of the Independent Set decision problem. Consider the following decider for this problem.

DecideIndependentSet( $G = (V, E), k$ ):

For each  $S \subseteq V$  such that  $|S| = k$ :

    bool  $\leftarrow$  True

    For every pair of two vertices  $(u, v)$  from the set  $S$ :

        If there is an edge between  $u$  and  $v$ :

            bool  $\leftarrow$  False

    If bool == True:

        return True

    Else:

        return False

The runtime of the above algorithm is  $T(n) = O((n^k)k^2)$ . This implies Independent Set which is NP-Hard has a poly-time solver implying  $P = NP$ . [Did we just solve the millennium problem again!?!]

**Problem 7 [6 points]**

Prove or disprove that the Halting problem is NP-Hard.

**Problem 8 [20 points]**

For definitions of  $A_{TM}$ ,  $\text{Halt}_{TM}$ ,  $\text{HaltB}_{TM}$  refer to the cheat sheet.

- a. Using undecidability of  $A_{TM}$ , show that  $\text{HaltB}_{TM}$  is undecidable.

- b. Using undecidability of  $\text{Halt}_{\text{TM}}$ , show that the following language is undecidable.

$$\text{Reg}_{\text{TM}} = \{\langle M \rangle \mid M \text{ is a TM and } L(M) \text{ is regular.}\}$$

*This page is for additional scratch work!*

# ECE 374 B Algorithms: Cheatsheet

## 1 Recursion

### Simple recursion

- **Reduction:** solve one problem using the solution to another.
- **Recursion:** a special case of reduction - reduce problem to a smaller instance of itself (self-reduction).

#### Definitions

- Problem instance of size  $n$  is reduced to one or more instances of size  $n - 1$  or less.
- For termination, problem instances of small size are solved by some other method as *base cases*

Arguably the most famous example of recursion. The goal is to move  $n$  disks one at a time from the first peg to the last peg.

Pseudocode: Tower of Hanoi

```
Hanoi(n, src, dest, tmp):
  if (n > 0) then
    Hanoi(n - 1, src, tmp, dest)
    Move disk n from src to dest
    Hanoi(n - 1, tmp, dest, src)
```

Tower of Hanoi

### Recurrences

Suppose you have a recurrence of the form  $T(n) = rT(n/c) + f(n)$ .

The *master theorem* gives a good asymptotic estimate of the recurrence. If the work at each level is:

Decreasing:  $rf(n/c) = \kappa f(n)$  where  $\kappa < 1$      $T(n) = O(f(n))$   
 Equal:  $rf(n/c) = f(n)$      $T(n) = O(f(n) \cdot \log_c n)$   
 Increasing:  $rf(n/c) = Kf(n)$  where  $K > 1$      $T(n) = O(n^{\log_c K})$

Some useful identities:

- Sum of integers:  $\sum_{k=1}^n k = \frac{n(n+1)}{2}$
- Geometric series closed-form formula:  $\sum_{k=0}^n ar^k = \frac{1-r^{n+1}}{1-r}$
- Logarithmic identities:  $\log(ab) = \log a + \log b$ ,  $\log(a/b) = \log a - \log b$ ,  $a^{\log_c b} = b^{\log_c a}$  ( $a, b, c > 1$ ).

### Backtracking

*Backtracking* is the algorithm paradigm involving guessing the solution to a single step in some multi-step process and recursing backwards if it doesn't lead to a solution. For instance, consider the longest increasing subsequence (LIS) problem. You can either check all possible subsequences:

Pseudocode: LIS - Naive enumeration

```
algLISNaive(A[1..n]):
  maxmax = 0
  for each subsequence B of A do
    if B is increasing and |B| > max then
      max = |B|
  return max
```

On the other hand, we don't need to generate every subsequence; we only need to generate the subsequences that are increasing:

Pseudocode: LIS - Backtracking

```
LIS_smaller(A[1..n], x):
  if n = 0 then return 0
  max = LIS_smaller(A[1..n - 1], x)
  if A[n] < x then
    max = max {max, 1 + LIS_smaller(A[1..(n - 1)], A[n])}
  return max
```

### Divide and conquer

*Divide and conquer* is an algorithm paradigm involving the decomposition of a problem into the same subproblem, solving them separately and combining their results to get a solution for the original problem.

Algorithm	Runtime	Space
Mergesort	$O(n \log n)$	$O(n \log n)$ $O(n)$ (if optimized)
Quicksort	$O(n^2)$ $O(n \log n)$ if using MoM	$O(n)$

We can divide and conquer multiplication like so:

$$bc = 10^n b_L c_L + 10^{n/2} (b_L c_R + b_R c_L) + b_R c_R.$$

We can rewrite the equation as:

$$bc = b(x)c(x) = (b_L x + b_R)(c_L x + c_R) = (b_L c_L)x^2 + ((b_L + b_R)(c_L + c_R) - b_L c_L - b_R c_R)x + b_R c_R,$$

Karatsuba's algorithm

Its running time is  $O(n^{\log_2 3}) = O(n^{1.585})$ .

### Linear time selection

The *median of medians* (MoM) algorithms give a element that is larger than  $\frac{3}{10}$ 's and smaller than  $\frac{7}{10}$ 's of the array elements. This is used in the linear time selection algorithm to find element of rank  $k$ .

Pseudocode: Quickselect with median of medians

```
Median-of-medians(A, i):
  sublists = |A|j+5 for j ← 0, 5, ..., len(A)
  medians = |sorted(sublist)|len(sublist)/2
  for sublist ∈ sublists

  // Base case
  if len(A) ≤ 5 return sorted(a)[i]

  // Find median of medians
  if len(medians) ≤ 5
    pivot = sorted(medians)[len(medians)/2]
  else
    pivot = Median-of-medians(medians, len/2)

  // Partitioning step
  low = |j for j ∈ A if j < pivot|
  high = |j for j ∈ A if j > pivot|

  k = len(low)
  if i < k
    return Median-of-medians(low, i)
  else if i > k
    return Median-of-medians(low, i-k-1)
  else
    return pivot
```

## Dynamic programming

Dynamic programming (DP) is the algorithm paradigm involving the computation of a recursive backtracking algorithm iteratively to avoid the recomputation of any particular subproblem.

### Longest increasing subsequence

The longest increasing subsequence problem asks for the length of a longest increasing subsequence in a unordered sequence, where the sequence is assumed to be given as an array. The recurrence can be written as:

$$LIS(i, j) = \begin{cases} 0 & \text{if } i = 0 \\ LIS(i-1, j) & \text{if } A[i] \geq A[j] \\ \max \begin{cases} LIS(i-1, j) \\ 1 + LIS(i-1, i) \end{cases} & \text{else} \end{cases}$$

Pseudocode: LIS - DP

**LIS-iterative**( $A[1..n]$ ):

$A[n+1] = \infty$

**for**  $j \leftarrow 0$  **to**  $n$

**if**  $A[j] \leq A[j]$  **then**  $LIS[0][j] = 1$

**for**  $i \leftarrow 1$  **to**  $n-1$  **do**

**for**  $j \leftarrow i$  **to**  $n-1$  **do**

**if**  $A[i] \geq A[j]$

$LIS[i, j] = LIS[i-1, j]$

**else**

$LIS[i, j] = \max \{ LIS[i-1, j], 1 + LIS[i-1, i] \}$

**return**  $LIS[n, n+1]$

### Edit distance

The edit distance problem asks how many edits we need to make to a sequence for it to become another one. The recurrence is given as:

$$Opt(i, j) = \min \begin{cases} \alpha_{x_i y_j} + Opt(i-1, j-1), \\ \delta + Opt(i-1, j), \\ \delta + Opt(i, j-1) \end{cases}$$

**Base cases:**  $Opt(i, 0) = \delta \cdot i$  and  $Opt(0, j) = \delta \cdot j$

Pseudocode: Edit distance - DP

$EDIST(A[1..m], B[1..n])$

**for**  $i \leftarrow 1$  **to**  $m$  **do**  $M[i, 0] = i\delta$

**for**  $j \leftarrow 1$  **to**  $n$  **do**  $M[0, j] = j\delta$

**for**  $i = 1$  **to**  $m$  **do**

**for**  $j = 1$  **to**  $n$  **do**

$$M[i][j] = \min \begin{cases} COST[A[i]][B[j]] \\ \quad + M[i-1][j-1], \\ \delta + M[i-1][j], \\ \delta + M[i][j-1] \end{cases}$$

## 2 Graph algorithms

### Graph basics

A graph is defined by a tuple  $G = (V, E)$  and we typically define  $n = |V|$  and  $m = |E|$ . We define  $(u, v)$  as the edge from  $u$  to  $v$ . Graphs can be represented as **adjacency lists**, or **adjacency matrices** though the former is more commonly used.

- *path*: sequence of *distinct* vertices  $v_1, v_2, \dots, v_k$  such that  $v_i v_{i+1} \in E$  for  $1 \leq i \leq k-1$ . The length of the path is  $k-1$  (the number of edges in the path).  
*Note*: a single vertex  $u$  is a path of length 0.
- *cycle*: sequence of *distinct* vertices  $v_1, v_2, \dots, v_k$  such that  $(v_i, v_{i+1}) \in E$  for  $1 \leq i \leq k-1$  and  $(v_k, v_1) \in E$ . A single vertex is not a cycle according to this definition.  
*Caveat*: Sometimes people use the term cycle to also allow vertices to be repeated; we will use the term *tour*.
- A vertex  $u$  is *connected* to  $v$  if there is a path from  $u$  to  $v$ .
- The *connected component* of  $u$ ,  $con(u)$ , is the set of all vertices connected to  $u$ .
- A vertex  $u$  can *reach*  $v$  if there is a path from  $u$  to  $v$ . Alternatively  $v$  can be reached from  $u$ . Let  $rch(u)$  be the set of all vertices reachable from  $u$ .

## Directed acyclic graphs

Directed acyclic graphs (dags) have an intrinsic ordering of the vertices that enables dynamic programming algorithms to be used on them. A *topological ordering* of a dag  $G = (V, E)$  is an ordering  $\prec$  on  $V$  such that if  $(u, v) \in E$  then  $u \prec v$ .

Pseudocode: Kahn's algorithm

```
Kahn( $G(V, E), u$ ):
  toposort ← empty list
  for  $v \in V$ :
     $in(v) \leftarrow |\{u \mid u \rightarrow v \in E\}|$ 
  while  $v \in V$  that has  $in(v) = 0$ :
    Add  $v$  to end of toposort
    Remove  $v$  from  $V$ 
    for  $w$  in  $u \rightarrow v \in E$ :
       $in(w) \leftarrow in(w) - 1$ 
  return toposort
```

Running time:  $O(n + m)$

- A dag may have multiple topological sorts.
- A topological sort can be computed by DFS, in particular by listing the vertices in decreasing post-visit order.

## DFS and BFS

Pseudocode: Explore (DFS/BFS)

```
Explore( $G, u$ ):
  for  $i \leftarrow 1$  to  $n$ :
    Visited[ $i$ ] ← False
  Add  $u$  to ToExplore and to  $S$ 
  Visited[ $u$ ] ← True
  Make tree  $T$  with root as  $u$ 
  while  $B$  is non-empty do
    Remove node  $x$  from  $B$ 
    for each edge  $(x, y)$  in  $Adj(x)$  do
      if Visited[ $y$ ] = False
        Visited[ $y$ ] ← True
        Add  $y$  to  $B, S, T$  (with  $x$  as parent)
```

Note:

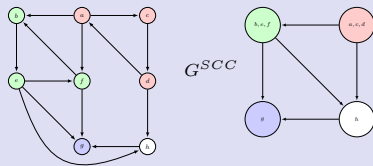
- If  $B$  is a queue, *Explore* becomes BFS.
- If  $B$  is a stack, *Explore* becomes DFS.

Pre and post numbering aids in analyzing the graph structure. By looking at the numbering we can tell if a edge  $(u, v)$  is a:

- **Forward edge:**  $pre(u) < pre(v) < post(v) < post(u)$
- **Backward edge:**  $pre(v) < pre(u) < post(u) < post(v)$
- **Cross edge:**  $pre(u) < post(u) < pre(v) < post(v)$

## Strongly connected components

- Given  $G$ ,  $u$  is *strongly connected to*  $v$  if  $v \in rch(u)$  and  $u \in rch(v)$ .
- A *maximal* group of  $G$ : vertices that are all strongly connected to one another is called a strong component.



Pseudocode: Metagraph - linear time

```
Metagraph( $G(V, E)$ ):
  Compute  $rev(G)$  by brute force
  ordering ← reverse postordering of  $V$  in  $rev(G)$ 
  by DFS( $rev(G), s$ ) for any vertex  $s$ 
  Mark all nodes as unvisited
  for each  $u$  in ordering do
    if  $u$  is not visited and  $u \in V$  then
       $S_u \leftarrow$  nodes reachable by  $u$  by DFS( $G, u$ )
      Output  $S_u$  as a strong connected component
   $G(V, E) \leftarrow G - S_u$ 
```

## Shortest paths

**Dijkstra's algorithm:**

Find minimum distance from vertex  $s$  to **all** other vertices in graphs *without* negative weight edges.

Pseudocode: Dijkstra

```
for  $v \in V$  do
   $d(v) \leftarrow \infty$ 
 $X \leftarrow \emptyset$ 
 $d(s, s) \leftarrow 0$ 
for  $i \leftarrow 1$  to  $n$  do
   $v \leftarrow \arg \min_{u \in V - X} d(u)$ 
   $X = X \cup \{v\}$ 
  for  $u$  in  $Adj(v)$  do
     $d(u) \leftarrow \min\{d(u), d(v) + \ell(v, u)\}$ 
return  $d$ 
```

Running time:  $O(m + n \log n)$  (if using a Fibonacci heap as the priority queue)

**Bellman-Ford algorithm:**

Find minimum distance from vertex  $s$  to **all** other vertices in graphs *without* negative cycles. It is a DP algorithm with the following recurrence:

$$d(v, k) = \begin{cases} 0 & \text{if } v = s \text{ and } k = 0 \\ \infty & \text{if } v \neq s \text{ and } k = 0 \\ \min \left\{ \begin{array}{l} \min_{u \in E} \{d(u, k-1) + \ell(u, v)\} \\ d(v, k-1) \end{array} \right\} & \text{else} \end{cases}$$

Base cases:  $d(s, 0) = 0$  and  $d(v, 0) = \infty$  for all  $v \neq s$ .

Pseudocode: Bellman-Ford

```
for each  $v \in V$  do
   $d(v) \leftarrow \infty$ 
 $d(s) \leftarrow 0$ 
for  $k \leftarrow 1$  to  $n - 1$  do
  for each  $v \in V$  do
    for each edge  $(u, v) \in E$  do
       $d(v) \leftarrow \min\{d(v), d(u) + \ell(u, v)\}$ 
return  $d$ 
```

Running time:  $O(nm)$

**Floyd-Warshall algorithm:**

Find minimum distance from *every* vertex to *every* vertex in a graph *without* negative cycles. It is a DP algorithm with the following recurrence:

$$d(i, j, k) = \begin{cases} 0 & \text{if } i = j \\ \infty & \text{if } (i, j) \notin E \text{ and } k = 0 \\ \min \left\{ \begin{array}{l} d(i, j, k-1) \\ d(i, k, k-1) + d(k, j, k-1) \end{array} \right\} & \text{else} \end{cases}$$

Then  $d(i, j, n-1)$  will give the shortest-path distance from  $i$  to  $j$ .

Pseudocode: Floyd-Warshall

```
Metagraph( $G(V, E)$ ):
  for  $i \in V$  do
    for  $j \in V$  do
       $d(i, j, 0) \leftarrow \ell(i, j)$ 
      (*  $\ell(i, j) \leftarrow \infty$  if  $(i, j) \notin E$ , 0 if  $i = j$  *)
  for  $k \leftarrow 0$  to  $n - 1$  do
    for  $i \in V$  do
      for  $j \in V$  do
         $d(i, j, k) \leftarrow \min \left\{ \begin{array}{l} d(i, j, k-1), \\ d(i, k, k-1) + d(k, j, k-1) \end{array} \right\}$ 
  for  $v \in V$  do
    if  $d(i, i, n-1) < 0$  then
      return "∃ negative cycle in  $G$ "
  return  $d(\cdot, \cdot, n-1)$ 
```

Running time:  $\Theta(n^3)$

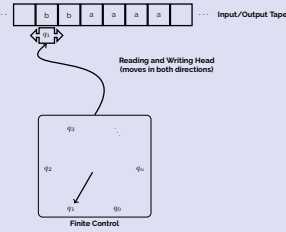


# ECE 374 B Reductions, P/NP, and Decidability: Cheatsheet

## Turing Machines

Turing machine is the simplest model of computation.

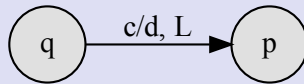
- Input written on (infinite) one sided tape.
- Special blank characters.
- Finite state control (similar to DFA).
- Every step: Read character under head, write character out, move the head right or left (or stay).
- Every TM  $M$  can be encoded as a string  $\langle M \rangle$



Transition Function:  $\delta : Q \times \Gamma \rightarrow Q \times \Gamma \times \{\leftarrow, \rightarrow, \square\}$

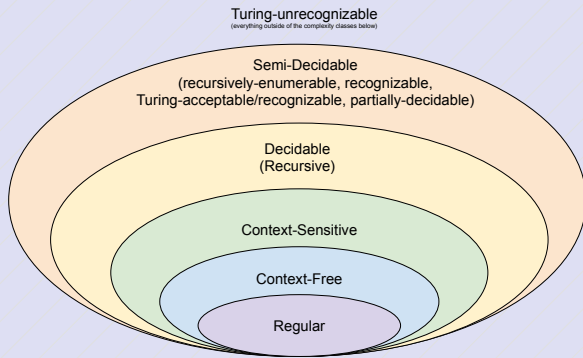
$\delta(q, c) = (p, d, \leftarrow)$

- $q$ : current state.
- $c$ : character under tape head.
- $p$ : new state.
- $d$ : character to write under tape head
- $\leftarrow$ : Move tape head left.

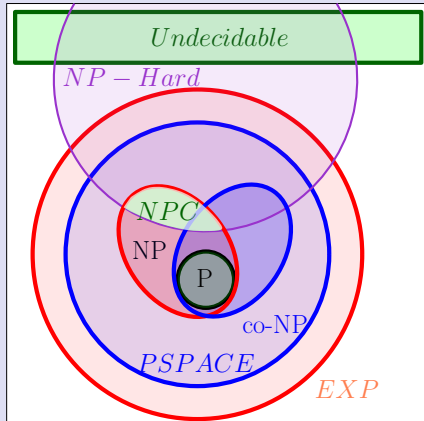


## Complexity Classes

### Computational Complexity Classes



### Algorithmic Complexity Classes (assuming $P \neq NP$ )



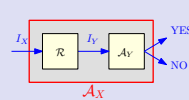
## Reductions

A general methodology to prove impossibility results.

- Start with some *known* hard problem  $X$
- Reduce  $X$  to your favorite problem  $Y$

If  $Y$  can be solved then so can  $X \implies Y$ . But we know  $X$  is hard so  $Y$  has to be hard too. On the other hand if we know  $Y$  is easy, then  $X$  has to be easy too.

The Karp reduction,  $X \leq_P Y$  suggests that there is a polynomial time reduction from  $X$  to  $Y$ .



Assuming

- $R(n)$ : running time of  $R$
  - $Q(n)$ : running time of  $A_Y$
- Running time of  $A_X$  is  $O(Q(R(n)))$

## Sample NP-complete problems

**CIRCUITSAT:** Given a boolean circuit, are there any input values that make the circuit output TRUE?

**3SAT:** Given a boolean formula in conjunctive normal form, with exactly three distinct literals per clause, does the formula have a satisfying assignment?

**INDEPENDENTSET:** Given an undirected graph  $G$  and integer  $k$ , what is there a subset of vertices  $\geq k$  in  $G$  that have no edges among them?

**CLIQUE:** Given an undirected graph  $G$  and integer  $k$ , is there a complete complete subgraph of  $G$  with more than  $k$  vertices?

**KPARTITION:** Given a set  $X$  of  $kn$  positive integers and an integer  $k$ , can  $X$  be partitioned into  $n$ ,  $k$ -element subsets, all with the same sum?

**3COLOR:** Given an undirected graph  $G$ , can its vertices be colored with three colors, so that every edge touches vertices with two different colors?

**HAMILTONIANPATH:** Given graph  $G$  (either directed or undirected), is there a path in  $G$  that visits every vertex exactly once?

**HAMILTONIANCYCLE:** Given a graph  $G$  (either directed or undirected), is there a cycle in  $G$  that visits every vertex exactly once?

**LONGESTPATH:** Given a graph  $G$  (either directed or undirected, possibly with weighted edges) and an integer  $k$ , does  $G$  have a path  $\geq k$  length?

• Remember a **path** is a sequence of distinct vertices  $[v_1, v_2, \dots, v_k]$  such that an edge exists between any two vertices in the sequence. A **cycle** is the same with the addition of an edge  $(v_k, v_1) \in E$ . A **walk** is a path except the vertices can be repeated.

• A formula is in conjunction normal form if variables are or'ed together inside a clause and then clauses are and'ed together:  $((x_1 \vee x_2 \vee x_3) \wedge (\overline{x_2} \vee x_4 \vee x_5))$ . Disjunctive normal form is the opposite  $((x_1 \wedge x_2 \wedge x_3) \vee (\overline{x_2} \wedge x_4 \wedge x_5))$ .

## Sample undecidable problems

**ACCEPTONINPUT:**  $A_{TM} = \{ \langle M, w \rangle \mid M \text{ is a TM and } M \text{ accepts on } w \}$

**HALTSONINPUT:**  $Hal_{TM} = \{ \langle M, w \rangle \mid M \text{ is a TM and halts on input } w \}$

**HALTONBLANK:**  $Hal_{B_{TM}} = \{ \langle M \rangle \mid M \text{ is a TM \& } M \text{ halts on blank input} \}$

**EMPTINESS:**  $E_{TM} = \{ \langle M \rangle \mid M \text{ is a TM and } L(M) = \emptyset \}$

**EQUALITY:**  $EQ_{TM} = \left\{ \langle M_A, M_B \rangle \mid \begin{array}{l} M_A \text{ and } M_B \text{ are TM's} \\ \text{and } L(M_A) = L(M_B) \end{array} \right\}$